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Se desarrollará un algoritmo de parada automática del robot KUKA KR3 R540 sobre el Sistema Operativo KUKA System Software (KSS) que contiene el controlador KRC4 compact. La programación del algoritmo se realizará desde el software WorkVisual 4.0 usando los bits del sistema para el modo de servicio Automático Externo del robot.

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Sistema de robótica colaborativa basado en el robot KUKA ...

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